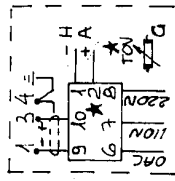


REG. Z. TACHIMETRICA:  
 REG. CON V. MAX SU RTS.  
 TACHO FEEDBACK:  
 SET WITH V. MAX ON RTS.  
 R1 = R2 = 10K  $\Omega$  W  
 PER VTD DA 60 a 200 V.

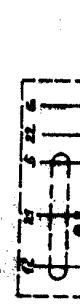
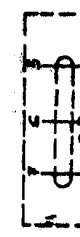


REG. Z. ARMATURA: REG.  
 CON "U" SU TOU  
 ARMATURE FEEDBACK  
 SET WITH "U" ON TOU  
 R1 = R2 CAPAC. (JUMP)  
 ROTORE V. MAX di RTS  
 MINIMO USCITA TOU =  
 = MAX 10V.  
 TURN V. MAX OF RTS  
 AT MINIMUM (OUT PUT  
 TOU = MAX 10V).

DESCRIZIONE  
 SCHEMA FUNZIONABILE  
 CT 30\_30\_75 / V5

308 Series Control Systems  
 Systems electronic di controllo di velocità  
 V. Ver. 15 - 2000 (Velocità) (minimo)

1.5.7.8.9.10.11.12.13.14.15.16.17.18.19.20.21.22.23.24.25.26.27.28.29.30.31.32.33.34.35.36.37.38.39.40.41.42.43.44.45.46.47.48.49.50.51.52.53.54.55.56.57.58.59.60.61.62.63.64.65.66.67.68.69.70.71.72.73.74.75.76.77.78.79.80.81.82.83.84.85.86.87.88.89.90.91.92.93.94.95.96.97.98.99.100.



SOLO PER:  
 (X) ONLY FOR:  
 CT 30\_30\_75 / V5

- MORSETT. CONTINUO CONTROL. T.B.
- ◎ MORSETT. ALIMENT. CONTROLLO T.B.
- SUPPLY CONTROL. T.B.
- ◇ MORSETT. POTENZA
- ◇ POWER. T.B.
- △ LEGGERA TRIMMER. accel / deceler. RLC / DEL. TIME
- ∨ MAX= VELOCITA' MAX / SPEED MAX
- ∨ MIN= VELOCITA' MIN / SPEED MIN
- I MAX= CORRENTE MAX. / MAX CURRENT
- STAB= STABILITA' / STABILITY

(\*) IN SERIE ALL'INDIRIZZO IN SERIE TO STOP